

The Analog to Digital Converter (ADC)

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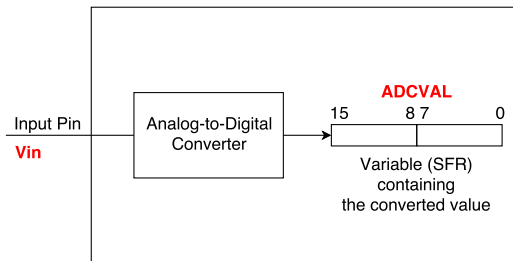
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What is an ADC?

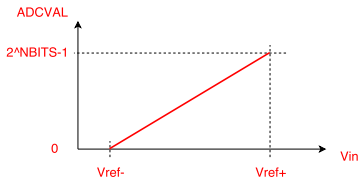
An ADC (Analog-to-Digital-Converter) is a circuit which gets an **analog voltage signal** (as input) and provides (to software) a **integer variable proportional** to the input signal.



ADC Characteristics

An ADC is characterised by:

- The **voltage range** of the input signal, V_{ref-} , V_{ref+}
 - the input signal must always be in the interval $[V_{ref-}, V_{ref+}]$
- The **resolution** in **bits** of the converter, $NBITS$.
- The ADC works by using a **linear law**:
 - If $V_{in} = V_{ref-}$, then $ADCVAL = 0$
 - If $V_{in} = V_{ref+}$, then $ADCVAL = 2^{NBITS} - 1$



$$ADCVAL = \left[(V_{in} - V_{ref-}) \frac{2^{NBITS} - 1}{V_{ref+} - V_{ref-}} \right]$$

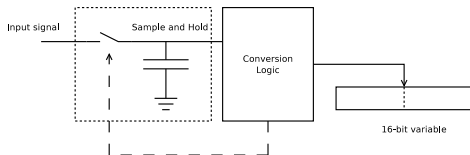
ADC Characteristics

- In general, $V_{ref-} = 0$ (GND) and $V_{ref+} = VDD$ (power supply voltage, i.e. 5 V or 3.3 V)
- In our Nucleo board, $VDD = 3.3$ V therefore $V_{ref+} = 3.3$ V
- In this case, the conversion law becomes:

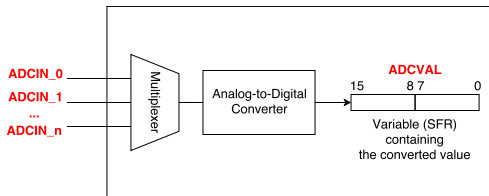
$$ADCVAL = \left[V_{in} \frac{2^{NBITS} - 1}{3.3} \right]$$

ADC: Basic working scheme

The ADC is a **sequential circuit** that performs conversion using a sequence of steps:



- 1 **Sample:** the signal is *sampled* by closing the switch and charging the capacitor; the duration of this phase is denoted as T_{smp}
- 2 **Conversion:** the switch is open and the sampled signal is *converted*; the result is stored in the 16-bit variable. The duration of this phase is denoted as T_{conv}
- 3 **End-of-conversion:** a proper bit is set to signal that the operation has been done.



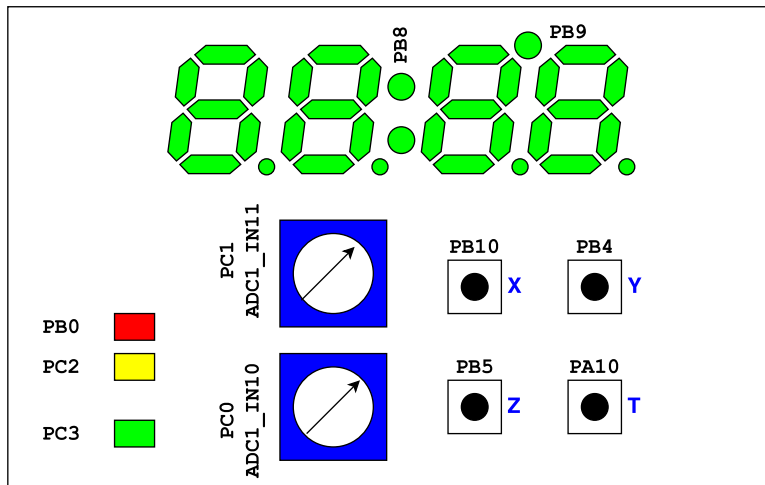
- In general, an ADC has **several inputs**
- But only **one input (channel) at time** can be selected for conversion (through the multiplexer)
- To perform conversion, the software must:
 - **Select the input channel** to be converted
 - **Start the conversion** (by setting a proper bit in a SFR)
 - **Wait for the end-of-conversion** (by checking a proper bit in a SFR),
or
 - **being notified** of the end-of-conversion through an **IRQ**

ADC inputs on STM32F401

- In the STM32F401 MCU, ADC inputs share the same pin of GPIO ports
- In particular, some GPIO pins can be programmed in order to be served as **analog input channel** (and no more used as digital I/O):

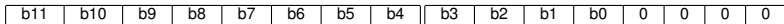
Pin	Analog Channel		Pin	Analog Channel
PA0	ADC1_IN0		PA1	ADC1_IN1
PA2	ADC1_IN2		PA3	ADC1_IN3
PA4	ADC1_IN4		PA5	ADC1_IN5
PA6	ADC1_IN6		PA7	ADC1_IN7
PB0	ADC1_IN8		PB1	ADC1_IN9
PC0	ADC1_IN10		PC1	ADC1_IN11
PC2	ADC1_IN12		PC3	ADC1_IN13
PC4	ADC1_IN14		PC5	ADC1_IN15

The Nucleo64 Addon Board (look at ADC settings)



ADC characteristics on STM32F4xx

- In the STM32F4xx MCUs, the ADCs have **configurable resolution**:
 - **6 bits**, range [0, 63]
 - **8 bits**, range [0, 255]
 - **10 bits**, range [0, 1023]
 - **12 bits**, range [0, 4095]
- The conversion result may be aligned **left** or **right** in the 16 bit result, e.g.:
- **12bit Left-Aligned**



- **12bit Right-Aligned**



The Software interface of ADCs

- Each ADC has several special function registers
- All of them are accessible by means of global variables called **ADC x** , where **x** is the number of the adc (our micro has only ADC1) (**ADC1**, **ADC2**, ...)
- The type of these variables is **ADC_TypeDef ***, i.e. pointers to a structure whose field are the SFR of the ADC

- Initialize an ADC:

```
void ADC_init(ADC_TypeDef * adc, int res, int align);
```

- **adc**, the ADC circuit
- **res**, the resolution in bits
 - **ADC_RES_6**
 - **ADC_RES_8**
 - **ADC_RES_10**
 - **ADC_RES_12**
- **align**, the bit alignment
 - **ADC_ALIGN_RIGHT**
 - **ADC_ALIGN_LEFT**

- **Configure the input(s):**

```
void ADC_channel_config(ADC_TypeDef * adc,  
                        GPIO_TypeDef * port,  
                        int pin, int chan);
```

- **adc**, the ADC circuit
- **port**, the GPIO port of the input
- **pin**, the GPIO pin of the input
- **chan**, the ADC channel associated to the input

- **Start an ADC circuit:**

```
void ADC_on(ADC_TypeDef * adc);
```

- **Stop an ADC circuit:**

```
void ADC_off(ADC_TypeDef * adc);
```

- Select a channel to convert:

```
void ADC_sample_channel(ADC_TypeDef * adc, int chan);
```

- **adc**, the ADC circuit
 - **chan**, the ADC channel to be converted
- Start a sample+conversion of the selected channel:

```
void ADC_start(ADC_TypeDef * adc);
```

- Check if a conversion has been completed:

```
int ADC_completed(ADC_TypeDef * adc);
```

- Read the converted value:

```
int ADC_read(ADC_TypeDef * adc);
```

Sampling the ADC and showing the value

```
#include <stdio.h>
#include "stm32_unict_lib.h"

void main(void)
{
    DISPLAY_init();

    ADC_init(ADC1, ADC_RES_8, ADC_ALIGN_RIGHT);
    ADC_channel_config(ADC1, GPIOC, 0, 10);
    ADC_on(ADC1);
    ADC_sample_channel(ADC1, 10);

    for (;;) {
        ADC_start(ADC1);
        while (!ADC_completed(ADC1)) {}

        int value = ADC_read(ADC1);
        char s[4];
        sprintf(s, "%4d", value);
        DISPLAY_puts(0, s);
    }
}
```

Exercise: Let's flash a LED with a variable period

- We want to make a **LED flash** (with a timer) with a period ranging from **50 to 500 ms**
- The period must be set using the trimmer in **PC0/ADC1_IN10**
- Let's initialize the timebase of a timer to 0.5 ms
- The auto-reload value must be in the range [100, 1000]
- If we set the ADC to 8 bit, we can use the formula:

$$ARR = ADCVAL \frac{1000 - 100}{255} + 100$$

LED flash with variable period

```
#include <stdio.h>
#include "stm32_unict_lib.h"

int new_arr_value = 100;

void main(void)
{
    DISPLAY_init();
    GPIO_init(GPIOB);    GPIO_config_output(GPIOB, 0);

    ADC_init(ADC1, ADC_RES_8, ADC_ALIGN_RIGHT);
    ADC_channel_config(ADC1, GPIOC, 0, 10);
    ADC_on(ADC1); ADC_sample_channel(ADC1, 10);

    TIM_init(TIM2);
    TIM_config_timebase(TIM2, 42000, 100);
    TIM_set(TIM2, 0); TIM_enable_irq(TIM2, IRQ_UPDATE);
    TIM_on(TIM2);

    for (;;) {
        ADC_start(ADC1);
        while (!ADC_completed(ADC1)) {}
        int value = ADC_read(ADC1);
        new_arr_value = value * 900/255 + 100;
        char s[4];
        sprintf(s, "%4d", new_arr_value / 2); // we will display the milliseconds
        DISPLAY_puts(0, s);
    }
}
```


LED flash with variable period (II)

```
void TIM2_IRQHandler(void)
{
    if (TIM_update_check(TIM2)) {
        GPIO_toggle(GPIOB, 0);
        TIM_update_clear(TIM2);
        TIM2->ARR = new_arr_value;
        // update the autoreload register with new value
    }
}
```

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