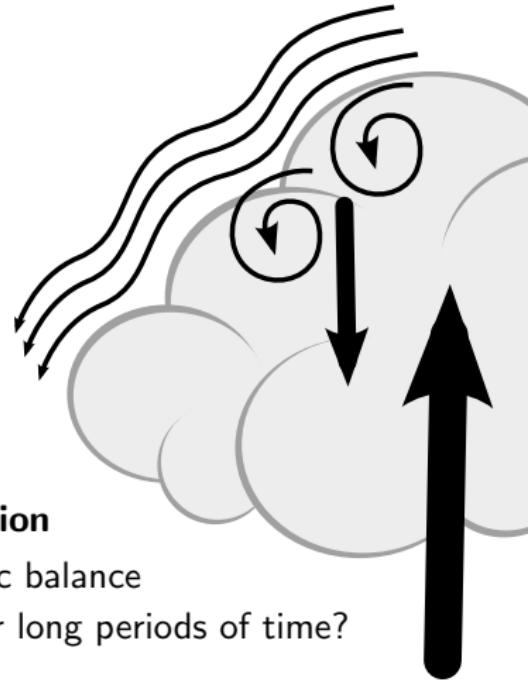
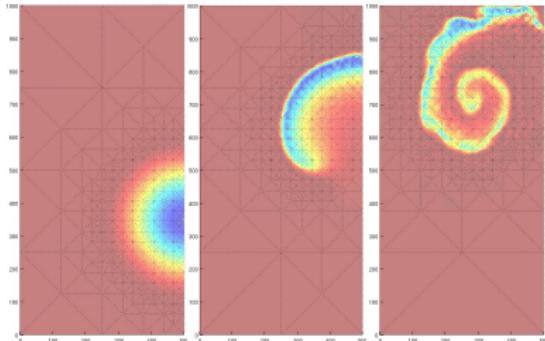


Well-balanced asymptotic preserving methods for the Euler equations with the gravity

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Application



JG|U

Meteorology: Cloud Simulation

Gravity induces hydrostatic balance

How do clouds evolve over long periods of time?

Multiscale phenomena of oceanographical, atmospherical flows

- wave speeds differ by several orders: $\|\mathbf{u}\| \ll c \Rightarrow M, Fr := \frac{\|\mathbf{u}\|}{c} \ll 1$
- typically $M \approx 10^{-2}$

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$$\frac{\max(|u| + c, |v| + c) \Delta t}{\Delta x} \leq 1$$

$$\max \left(\left(1 + \frac{1}{\mathbf{M}} \right) \sqrt{u^2 + v^2} \right) \frac{\Delta t}{\Delta x} \leq 1$$

- number of time steps $\mathcal{O}(1/\mathbf{M})$

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-**low Mach / low Froude number problem**

[Bijl & Wesseling ('98), Klein et al. ('95, '01), Meister ('99, '01),
Munz & Park ('05), Degond, S. Jin, J.-G. Liu ('07), Degond, Tang ('11),
Haack, S. Jin, J.-G. Liu ('12),
Bispen, Arun, ML, Noelle ('14), Noelle, Bispen, Arun, ML, Munz ('14), ...]

Cancelation problem

- Sesterhenn et al. ('99)

- “pressure term” $\frac{1}{2\mathbf{M}^2} \nabla h^2 \implies$

but **round off errors** can yield the **cancelation** effects

leading order error in the pressure term $\approx \frac{1}{\mathbf{M}^2} \epsilon_1 \mathcal{O}\left(\frac{1}{\mathbf{M}^2}\right) \approx \mathcal{O}(1) !$

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Accuracy problem

- numerical viscosity of upwind methods depends on M
- truncation error grows as $M \rightarrow 0$ [Guillard, Viozat ('99), Rieper ('10)]

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Accuracy problem

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- AIM:

- large time step scheme: Δt does not depend on M
- efficient scheme for advection effects
- stability and accuracy of the scheme is independent on $M \rightarrow AP$

Asymptotic preserving schemes

S.Jin&Pareschi('01), Gosse&Toscani('02), Degond et al.('11), ...

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Goal 1: *Derive a scheme, which gives a consistent approximation of the limiting equations for any $\varepsilon = M \rightarrow 0$*

Goal 2: *Derive a scheme, which is uniformly accurate with respect to $\varepsilon = M$, if $\varepsilon = M \rightarrow 0$*

Euler equations with gravity

Compressible Euler equations

$$\partial_t \rho' + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\partial_t (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u} + p' \text{Id}) = -\rho' g \mathbf{k} \equiv -\rho' g \begin{pmatrix} 0 \\ 0 \\ -1 \end{pmatrix}$$

$$\partial_t (\rho \theta)' + \nabla \cdot (\rho \theta \mathbf{u}) = 0$$

with background state \bar{p} , $\bar{\rho}$, $\bar{\theta}$ in **hydrostatic balance**

$$\boxed{\partial_z \bar{p} = -\bar{\rho}g}$$

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State variables: $\mathbf{w} = [\rho', \rho u_1, \rho u_2, \rho u_3, (\rho \theta)']^\top$

State equation

$$\boxed{p = p_0 \left(\frac{R \rho \theta}{p_0} \right)^\gamma}$$

- Potential temperature $\theta := T/\pi$
- Exner-pressure $\pi(z) := 1 - \frac{gz}{c_p \theta}$

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Non-dimensional formulation in $(\rho', \mathbf{q} \equiv (\rho u_1, \rho u_2, \rho u_3), (\rho \theta)')$

$$\partial_t \rho' + \nabla \cdot (\rho \mathbf{u}) = 0$$

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- following Klein we consider $\gamma M^2 = Fr^2$; and set $\varepsilon := \sqrt{\gamma}M$

$$\begin{aligned}\partial_t \rho' + \nabla \cdot (\rho \mathbf{u}) &= 0 \\ \partial_t (\rho \mathbf{u}) + \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u} + \frac{1}{\varepsilon^2} p' \text{Id}) &= -\frac{1}{\varepsilon^2} \rho' \mathbf{k} \\ \partial_t (\rho \theta)' + \nabla \cdot (\rho \theta \mathbf{u}) &= 0\end{aligned}$$

Asymptotic analysis as $\varepsilon \rightarrow 0$

- Hilbert expansion

$$f = (f^{(0)} + \varepsilon f^{(1)}) + \varepsilon^2 f^{(2)} = \bar{f} + f'$$

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- momentum eqs. \implies

$$p_z^{(0)} = -\rho^{(0)}, \quad p_z^{(1)} = -\rho^{(1)} \tag{1}$$

- due to the state eq. $\implies \rho^{(0)} = \rho^{(0)}(t, z), \theta^{(0)} = \theta^{(0)}(t, z),$
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- non-dimensional state eq.

$$p = (\rho\theta)^\gamma \tag{2}$$

\implies

$$(\rho\theta^{(i)})^{\gamma-1}(\rho\theta^{(i)})_z = -\frac{1}{\gamma}\rho^{(i)} \tag{3}$$

for $i = 0, 1$

Limiting system as $\varepsilon \rightarrow 0$

If $\theta^{(0)}, \theta^{(1)} = \text{const.}$, then the leading order terms $i = 0, 1$

$$\rho^{(i)} = \frac{1}{\theta^{(i)}} \left(1 - \frac{(\gamma-1)z}{\gamma\theta^{(i)}} \right)^{\frac{1}{\gamma-1}} \cong \frac{p_0}{R\bar{\theta}} \pi^{c_v/R} \quad \pi(z) = 1 - \frac{gz}{c_p\theta} \text{ Exner pressure}$$

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$$\begin{aligned} \nabla \cdot (\rho^{(0)} \mathbf{u}^{(0)}) &= 0 \\ (\rho^{(0)} \mathbf{u}^{(0)})_t + \nabla \cdot (\rho^{(0)} \mathbf{u}^{(0)} \otimes \mathbf{u}^{(0)}) + \nabla p^{(2)} &= -\rho^{(2)} \mathbf{k} \end{aligned} \quad (4)$$

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Does a numerical scheme give a consistent and order preserving approximation of (4) ?

Time discretization

Key idea:

- semi-implicit time discretization: splitting into the linear and nonlinear part
- linear operator models gravitational and acoustic waves are treated implicitly
- rest nonlinear terms are treated explicitly

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- rest nonlinear terms are treated explicitly

$$\frac{\partial \mathbf{w}}{\partial t} = -\nabla \cdot \mathbf{F}(\mathbf{w}) + \mathbf{S}(\mathbf{w}) \equiv \mathcal{L}(\mathbf{w}) + \mathcal{N}(\mathbf{w})$$

$$\mathbf{w} = (\rho', \rho \mathbf{u}, \rho \theta')^T,$$

[Restelli ('07), Giraldo & Restelli ('10)]

[Yelash, Müller, M.L., Giraldo, Wirth (JCP'14)] ... Euler eq. DG-method

[Bispen, Arun, M.L., Noelle (CiCP'14)] ... shallow water eq.

Linear/Non-linear splitting

$$\frac{\partial \mathbf{w}}{\partial t} = -\nabla \cdot \mathbf{F}(\mathbf{w}) + \mathbf{S}(\mathbf{w}) \equiv \mathcal{L}(\mathbf{w}) + \mathcal{N}(\mathbf{w})$$

$$\begin{aligned}\partial_t \rho' &+ \nabla \cdot (\rho \mathbf{u}) + \nabla \cdot \mathbf{0} &= 0 \\ \partial_t (\rho \mathbf{u}) &+ \nabla \cdot (\rho \mathbf{u} \otimes \mathbf{u} + \frac{1}{\varepsilon^2} p' \text{Id}) &= -\frac{1}{\varepsilon^2} \rho' \mathbf{k} \\ \partial_t (\rho \theta)' &+ \nabla \cdot (\bar{\theta} \rho \mathbf{u}) + \nabla \cdot (\theta' \rho \mathbf{u}) &= 0\end{aligned}$$

linear part for the Euler system

$$\partial_t \mathbf{w} = \mathcal{L}(\mathbf{w})$$

$$\mathbf{w} := \begin{pmatrix} \rho' \\ \rho u \\ \rho v \\ \rho w \\ (\rho\theta)' \end{pmatrix} \quad \mathcal{L}(\mathbf{w}) := - \begin{pmatrix} \operatorname{div}(\rho\mathbf{u}) \\ \frac{1}{\varepsilon^2} \partial p'/\partial x \\ \frac{1}{\varepsilon^2} \partial p'/\partial y \\ \frac{1}{\varepsilon^2} \partial p'/\partial z + \frac{1}{\varepsilon^2} \rho' \\ \operatorname{div}(\bar{\theta}\rho\mathbf{u}) \end{pmatrix}$$

- linearized version of p' : $p' = \frac{c_p \bar{p}}{c_v \bar{\rho} \bar{\theta}} (\rho\theta)'$

[Yelash, Müller, M.L., Giraldo, Wirth (JCP'14)]

Properties of the linear subsystem

$$\mathbf{w}'_t + \nabla \cdot \mathcal{F}_L(\mathbf{w}', \bar{\mathbf{w}}) = S(\mathbf{w}'), \quad \mathcal{F}_L = \begin{bmatrix} \mathbf{q}^T \\ \frac{\bar{c}^2}{\bar{\theta}\varepsilon^2} (\rho\theta)' \mathbf{1} \\ \mathbf{q}^T \bar{\theta} \end{bmatrix}, \quad S = \begin{bmatrix} 0 \\ -\frac{\rho'}{\varepsilon^2} \mathbf{k} \\ 0 \end{bmatrix} \quad (5)$$

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- matrix pencil:

$$\mathbb{P}(\mathbf{w}', \mathbf{n}) = \sum_{i=1}^3 \frac{d\mathcal{F}_{L_i}}{d\mathbf{w}'} n_i = \begin{bmatrix} 0 & \mathbf{n}^T & 0 \\ 0 & 0 & \frac{\bar{c}^2}{\bar{\theta}\varepsilon^2} \mathbf{n} \\ 0 & \bar{\theta} \mathbf{n}^T & 0 \end{bmatrix}$$

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- eigenvalues:

$$\lambda_1 = -\frac{\bar{c}}{\varepsilon}, \quad \lambda_2 = \lambda_3 = \lambda_4 = 0, \quad \lambda_5 = \frac{\bar{c}}{\varepsilon}$$

⇒ **stiff linear subsystem**

Properties of the non-linear subsystem

$$\mathbf{w}'_t + \nabla \cdot \mathcal{F}_{NL}(\mathbf{w}', \bar{\mathbf{w}}) = 0, \quad \mathcal{F}_{NL} = \begin{bmatrix} 0 \\ \frac{\mathbf{q}\mathbf{q}^T}{\bar{\rho}+\rho'} \\ \mathbf{q}^T \frac{(\rho\theta)'}{\bar{\rho}+\rho'} \end{bmatrix} \quad (6)$$

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- eigenvalues:

$$\lambda_1 = 0, \quad \lambda_2 = \lambda_3 = \lambda_4 = \mathbf{u} \cdot \mathbf{n}, \quad \lambda_5 = 2\mathbf{u} \cdot \mathbf{n}$$

⇒ **non-stiff nonlinear subsystem**

Semi-implicit time discretization

- first order IMEX scheme

$$\begin{aligned}\mathbf{w}^{n+1} &= \mathbf{w}^n + \Delta t \mathcal{L}(\mathbf{w}^{n+1}) + \Delta t \mathcal{N}(\mathbf{w}^n) \\ &= \mathbf{w}^n - \Delta t \nabla \cdot \mathcal{F}_L(\mathbf{w}^{n+1}) + \Delta t S(\mathbf{w}^{n+1}) - \Delta t \nabla \cdot \mathcal{F}_{NL}(\mathbf{w}^n)\end{aligned}$$

Higher time discretization

- **RK2CN scheme:** (midpoint for the nonlinear & trap rule for the linear part)

$$\begin{aligned}\mathbf{w}^{n+\frac{1}{2}} &= \mathbf{w}^n - \frac{\Delta t}{2} \nabla \cdot \mathcal{F}_{NL}(\mathbf{w}^n) - \frac{\Delta t}{2} \nabla \cdot \mathcal{F}_L(\mathbf{w}^{n+\frac{1}{2}}) + \frac{\Delta t}{2} S(\mathbf{w}^{n+\frac{1}{2}}) \\ \mathbf{w}^{n+1} &= \mathbf{w}^n - \Delta t \nabla \cdot \mathcal{F}_{NL}(\mathbf{w}^{n+\frac{1}{2}}) - \frac{\Delta t}{2} \nabla \cdot [\mathcal{F}_L(\mathbf{w}^n) + \mathcal{F}_L(\mathbf{w}^{n+1})] \\ &\quad + \frac{\Delta t}{2} [S(\mathbf{w}^n) + S(\mathbf{w}^{n+1})],\end{aligned}$$

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- **ARS (2,2,2) scheme:** (Boscarino, Pareschi, Russo)

$$\mathbf{w}_1 = \mathbf{w}^n$$

$$\mathbf{w}_2 + \Delta t \gamma [\nabla \cdot \mathcal{F}_L(\mathbf{w}_2) + S(\mathbf{w}_2)] = \Delta t \gamma \nabla \cdot \mathcal{F}_{NL}(\mathbf{w}^n)$$

$$\begin{aligned}\mathbf{w}^{n+1} + \Delta t \gamma [\nabla \cdot \mathcal{F}_L(\mathbf{w}^{n+1}) + S(\mathbf{w}^{n+1})] &= \mathbf{w}^n - \Delta t \gamma [\delta \nabla \cdot \mathcal{F}_{NL}(\mathbf{w}^n) \\ &\quad + (1-\delta) \nabla \cdot \mathcal{F}_{NL}(\mathbf{w}_2)] - \Delta t [(1-\gamma) (\nabla \cdot \mathcal{F}_L(\mathbf{w}_2) + S(\mathbf{w}_2))],\end{aligned}$$

$$\gamma = 1 - 1/\sqrt{2}; \quad \delta = 1 - 1/(2\gamma)$$

Higher order time discretization

- BDF2 scheme:

$$\begin{aligned}\mathbf{w}^{n+1} = & \alpha_0 \mathbf{w}^n + \alpha_1 \mathbf{w}^{n-1} \\ & + \nabla \cdot \left\{ \beta \mathcal{F}_L(\mathbf{w}^{n+1}) + \beta_0 \mathcal{F}_{NL}(\mathbf{w}^n) + \beta_1 \mathcal{F}_{NL}(\mathbf{w}^{n-1}) \right\} \\ & - \beta S(\mathbf{w}^{n+1})\end{aligned}$$

$$\alpha_0 = \frac{4}{3}; \quad \alpha_1 = -\frac{1}{3}; \quad \beta = -\frac{2}{3} \Delta t; \quad \beta_0 = -\frac{4}{3} \Delta t; \quad \beta_1 = \frac{2}{3} \Delta t$$

Spatial discretization

Finite Volume update

$$\mathcal{L}(\mathbf{w}^\ell) = - \sum_{k=1}^2 \frac{1}{\Delta x_k} \delta_{x_k} \mathcal{F}_{L_k}(\mathbf{w}^\ell) + S(\mathbf{w}^\ell), \quad \ell = n, n+1$$

$$\mathcal{N}(\mathbf{w}^\ell) = - \sum_{k=1}^2 \frac{1}{\Delta x_k} \delta_{x_k} \mathcal{F}_{NL_k}(\mathbf{w}^\ell), \quad \ell = n, n-1, n+1/2$$

$$\delta_x f_i \equiv f_{i+1/2} - f_{i-1/2}$$

\mathcal{F}_L :

- Multi-d evolution operator in [Arun, M.L., Kraft, Prasad (2009)] ... multi-d Riemann solver, see [Yelash, Müller, M.L., Giraldo, Wirth (2014)]
- Central finite-difference scheme (CFD)

\mathcal{F}_{NL} :

- evolution along the characteristics
- approximate Riemann solver (e.g. Rusanov, van Leer, etc.)
- comparisons for the shallow water eqs. in [Bispen, Arun, M.L, Noelle (2014)]

AP analysis of the IMEX finite volume scheme

- Consider: CFD-implicitly and Rusanov-flux explicitly, first order IMEX, periodic BC

$$(\mathbb{1} + \Delta t A) \mathbf{W}^{n+1} = RHS(\hat{\mathbf{W}}), \text{ e.g. } \hat{\mathbf{W}} = \mathbf{W}^n$$

$$A = \begin{bmatrix} 0 & \mathfrak{D}_{x_1} & \mathfrak{D}_{x_2} & \mathfrak{D}_{x_3} & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_1} \bar{C}^2 \bar{\Theta}^{-1} \\ 0 & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_2} \bar{C}^2 \bar{\Theta}^{-1} \\ \frac{1}{\varepsilon^2} \mathbb{1} & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_3} \bar{C}^2 \bar{\Theta}^{-1} \\ 0 & \mathfrak{D}_{x_1} \bar{\Theta} & \mathfrak{D}_{x_2} \bar{\Theta} & \mathfrak{D}_{x_3} \bar{\Theta} & 0 \end{bmatrix}$$

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- Consider: CFD-implicitly and Rusanov-flux explicitly, first order IMEX, periodic BC

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$$A = \begin{bmatrix} 0 & \mathfrak{D}_{x_1} & \mathfrak{D}_{x_2} & \mathfrak{D}_{x_3} & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_1} \bar{C}^2 \bar{\Theta}^{-1} \\ 0 & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_2} \bar{C}^2 \bar{\Theta}^{-1} \\ \frac{1}{\varepsilon^2} \mathbb{1} & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_3} \bar{C}^2 \bar{\Theta}^{-1} \\ 0 & \mathfrak{D}_{x_1} \bar{\Theta} & \mathfrak{D}_{x_2} \bar{\Theta} & \mathfrak{D}_{x_3} \bar{\Theta} & 0 \end{bmatrix}$$

- Gauss elimination (Schur complement)

$$(\mathbb{1} + \frac{\Delta t^2}{\varepsilon^2} B) \begin{pmatrix} \rho' \\ (\rho \theta)' \end{pmatrix} = \begin{pmatrix} \hat{\rho}' - \Delta t \nabla_h \cdot \hat{\mathbf{Q}} \\ (\hat{\rho} \theta)' - \Delta t \nabla_h \cdot (\bar{\Theta} \hat{\mathbf{Q}}) \end{pmatrix}$$

$$B = \begin{bmatrix} -\mathfrak{D}_{x_3} & -\Delta_h \bar{C}^2 \bar{\Theta}^{-1} \\ -\mathfrak{D}_{x_3} \bar{\Theta} & -\nabla_h \cdot ((\mathbb{1}_3 \otimes \bar{\Theta}) * \nabla_h \bar{C}^2 \bar{\Theta}^{-1}) \end{bmatrix}$$

AP analysis of the IMEX finite volume scheme

$$\left(\mathbb{1} + \frac{\Delta t^2}{\varepsilon^2} B \right) \begin{pmatrix} \rho' \\ (\rho\theta)' \end{pmatrix} = \begin{pmatrix} \hat{\rho}' - \Delta t \nabla_h \cdot \hat{\mathbf{Q}} \\ (\hat{\rho}\theta)' - \Delta t \nabla_h \cdot (\bar{\Theta} \hat{\mathbf{Q}}) \end{pmatrix} \quad (7)$$

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$$\left[\mathbb{1} + \frac{\Delta t^2}{\varepsilon^2} E \right] (\rho\theta)' = (\hat{\rho}\theta)' - \Delta t \bar{\Theta} \nabla_h \cdot \hat{\mathbf{Q}} - \frac{\Delta t^2}{\varepsilon^2} \mathfrak{D}_{x_3} ((\hat{\rho}\theta)' - \bar{\Theta} \hat{\rho}')$$

$$E := -(\Delta_h \bar{C}^2 + \mathfrak{D}_{x_3})$$

AP analysis of the IMEX finite volume scheme

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- 3 $E^2 \mathbf{x} = 0 \Rightarrow E \mathbf{x} = 0$ thus algebraic and geometric multiplicity of 0 equals
 \Rightarrow

$$\left(\mathbb{1} + \frac{\Delta t^2}{\varepsilon^2} E \right)^{-1} = \pi_{\mathcal{N}(E)} + \mathcal{O}(\varepsilon^2)$$

$$4 \quad \mathcal{R}(E) = \mathcal{N}(E)^\perp = \mathcal{N}(\nabla_h)^\perp = \mathcal{R}(\nabla_h^T) = \mathcal{R}(\nabla_h \cdot) \Rightarrow$$

$$((\rho\theta)')^{n+1} - \hat{\rho}\hat{\theta}', (\rho')^{n+1} - \hat{\rho}', \nabla_h \cdot \mathbf{Q}^{n+1} = \mathcal{O}(\varepsilon^2)$$

AP ✓

Well-Balancing

- Consider: Lineal/Non-lineal splitting, IMEX with CFD (implicit) and Rusanov (expl.)
- Assume we start from the hydrostatic equilibrium, i.e. $\rho' = 0 = (\rho\theta)', \mathbf{u} = 0$.
- Q: Does the method preserves this equilibrium on the discrete level?

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⇒ it follows from the construction:

Well-balancing cont....

$$(\mathbb{1} + \Delta t A) \mathbf{W}^{n+1} = RHS(\mathbf{W}^n) \equiv \mathbf{0},$$

$$A = \begin{bmatrix} 0 & \mathfrak{D}_{x_1} & \mathfrak{D}_{x_2} & \mathfrak{D}_{x_3} & 0 \\ 0 & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_1} \bar{C}^2 \bar{\Theta}^{-1} \\ 0 & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_2} \bar{C}^2 \bar{\Theta}^{-1} \\ \frac{1}{\varepsilon^2} \mathbb{1} & 0 & 0 & 0 & \frac{1}{\varepsilon^2} \mathfrak{D}_{x_3} \bar{C}^2 \bar{\Theta}^{-1} \\ 0 & \mathfrak{D}_{x_1} \bar{\Theta} & \mathfrak{D}_{x_2} \bar{\Theta} & \mathfrak{D}_{x_3} \bar{\Theta} & 0 \end{bmatrix}$$

Well-balancing cont....

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$\mathbb{1} + \Delta t A$ is non-singular $\Rightarrow \mathbf{W}^{n+1} = \mathbf{0}$

it preserves this hydrostatic equilibrium

WB ✓

Numerical experiments

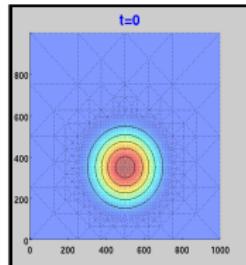
Test 1: rising warm air bubble

- bubble with a cosine profile in $\theta = \bar{\theta} + \theta'$:

$$\theta' = \begin{cases} 0 & r > r_C, r = \|\mathbf{x} - \mathbf{x}_C\| \\ 0.25[1 + \cos(\pi_c r / r_C)] & r \leq r_C \end{cases}$$

$$\mathbf{x}_C = (500, 350), r_C = 250m, \bar{\theta} = 300K,$$

$$\mathbf{x} \in [0, 1000]^2, t \in [0, 700]$$



AP Property for the Euler eqs.: $\|\nabla_h \cdot \mathbf{Q}^\varepsilon\| = \mathcal{O}(\varepsilon^2)$

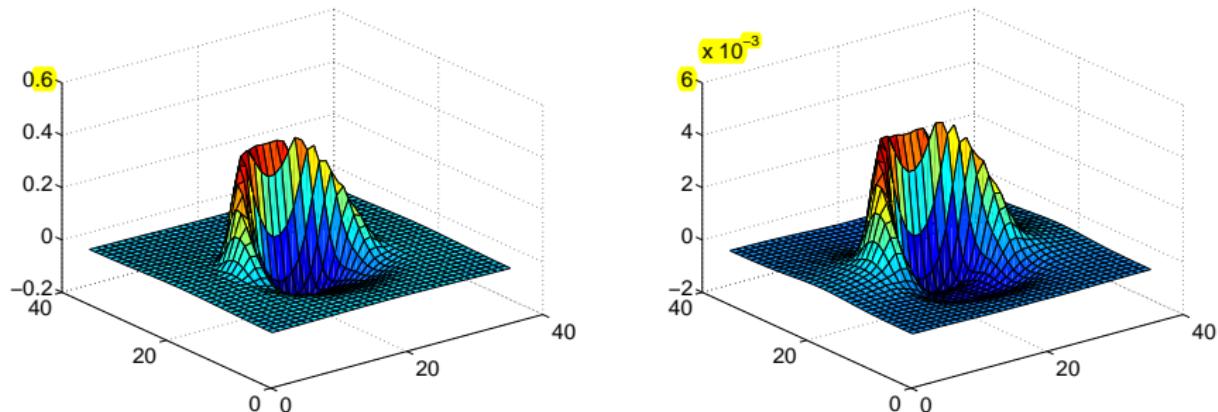


Figure: Warm bubble test; $\epsilon = 0.01, 0.001$, 40×40 grid.

AP Property for the Euler eqs.: $\|\nabla_h \cdot \mathbf{Q}^\varepsilon\| = \mathcal{O}(\varepsilon^2)$

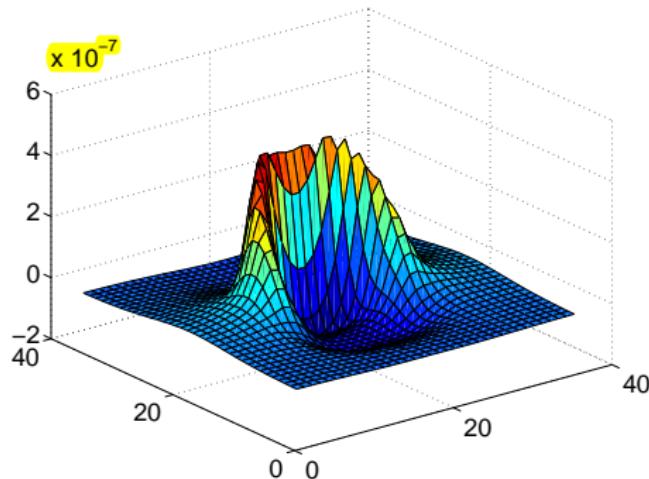


Figure: Warm bubble test; $\varepsilon = 10^{-5}$, 40×40 grid.

Experimental order of convergence for the IMEX ARS(2,2,2)

N	$\varepsilon = 10^{-3}$					
	L^1 -error ρ'	EOC ρ'	L^1 -error m	EOC m	L^1 -error $(\rho\theta)'$	EOC $(\rho\theta)'$
20	1.756e-07		5.287e-03		1.214e-07	
40	5.783e-08	1.6021	1.548e-03	1.7725	2.812e-08	2.1097
80	1.802e-08	1.6823	4.602e-04	1.7496	1.177e-08	1.2570
160	9.745e-09	0.8867	1.384e-04	1.7339	7.039e-09	0.7415

N	$\varepsilon = 10^{-5}$					
	L^1 -error ρ'	EOC ρ'	L^1 -error m	EOC m	L^1 -error $(\rho\theta)'$	EOC $(\rho\theta)'$
20	5.261e-07		2.676e-02		5.261e-07	
40	9.550e-11	12.4275	1.547e-03	4.1126	9.548e-11	12.4278
80	1.860e-12	5.6823	4.600e-04	1.7494	1.102e-12	6.4373
160	1.287e-12	0.5309	1.374e-04	1.7428	1.131e-12	-0.0381

Second order BDF scheme

SWE travelling vortex, $\varepsilon \in \{0.8, 10^{-3}, 10^{-5}\}$, $CFL_u = 0.3, T = 0.1$

N	L^1 -error in z	EOC z	L^1 -error in m_1	EOC m_1	L^1 -error in m_2	EOC m_2
20	5.035e-02	1.9389	0.10805	1.6333	0.22831	1.5043
40	1.257e-02	2.0020	0.02783	1.9570	0.05553	2.0398
80	3.244e-03	1.9542	0.00722	1.9462	0.01411	1.9765
160	8.148e-04	1.9932	0.00186	1.9561	0.00371	1.9281
N	L^1 -error in z	EOC z	L^1 -error in m_1	EOC m_1	L^1 -error in m_2	EOC m_2
20	9.355e-08	2.1659	0.11412	1.6103	0.23531	1.5518
40	1.643e-08	2.5098	0.02777	2.0388	0.05563	2.0805
80	3.109e-09	2.4016	0.00720	1.9485	0.01435	1.9550
160	7.819e-10	1.9911	0.00187	1.9449	0.00379	1.9200
N	L^1 -error in z	EOC z	L^1 -error in m_1	EOC m_1	L^1 -error in m_2	EOC m_2
20	9.355e-12	2.1661	0.11412	1.6103	0.23531	1.5518
40	1.642e-12	2.5099	0.02777	2.0388	0.05563	2.0805
80	3.105e-13	2.4030	0.00720	1.9485	0.01435	1.9550
160	7.811e-14	1.9912	0.00187	1.9449	0.00379	1.9200

Table: EOC of the second order BDF CFD/Rusanov scheme (elliptic approach)

Second order ARS(2,2,2) scheme

SWE travelling vortex, $\varepsilon \in \{0.8, 10^{-3}, 10^{-5}\}$, $CFL_u = 0.45$, $T = 0.1$

N	L^1 -error in z	EOC z	L^1 -error in m_1	EOC m_1	L^1 -error in m_2	EOC m_2
20	4.885e-02	1.9812	0.10303	1.7016	0.21995	1.5502
40	1.243e-02	1.9743	0.02671	1.9476	0.05282	2.0580
80	3.231e-03	1.9442	0.00688	1.9567	0.01307	2.0152
160	8.153e-04	1.9866	0.00177	1.9588	0.00340	1.9429
N	L^1 -error in z	EOC z	L^1 -error in m_1	EOC m_1	L^1 -error in m_2	EOC m_2
20	1.120e-07	2.1192	0.10957	1.6468	0.22691	1.5922
40	2.223e-08	2.3330	0.02658	2.0436	0.05295	2.0995
80	6.223e-09	1.8369	0.00685	1.9560	0.01332	1.9911
160	2.506e-09	1.3123	0.00178	1.9480	0.00349	1.9340
N	L^1 -error in z	EOC z	L^1 -error in m_1	EOC m_1	L^1 -error in m_2	EOC m_2
20	1.126e-11	2.1139	0.10957	1.6467	0.22691	1.5922
40	1.785e-12	2.6572	0.02658	2.0435	0.05295	2.0995
80	5.225e-13	1.7721	0.00685	1.9560	0.01332	1.9911
160	3.159e-13	0.7258	0.00178	1.9479	0.00349	1.9341

Table: EOC of the second order ARS (2,2,2,) CFD/Rusanov scheme (elliptic approach)