

## DEFINIZIONE PER CASI

● SIANO  $M_1(\vec{x}), \dots, M_k(\vec{x})$  PREDICATI DECIDIBILI TALI CHE

-  $M_1(\vec{x}) \vee \dots \vee M_k(\vec{x}) \equiv \underline{\text{true}}$ ,  $\forall \vec{x}$

-  $M_i(\vec{x}) \wedge M_j(\vec{x}) \equiv \underline{\text{false}}$ ,  $\forall \vec{x} \forall i \neq j$

CIOE', PER OGNI  $\vec{x}$ , UNO ED UNO SOLO TRA

$M_1(\vec{x}), \dots, M_k(\vec{x})$  E' VERO.

● SIANO  $f_1(\vec{x}), \dots, f_k(\vec{x})$  FUNZIONI CALCOLABILI

(ANCHE PARZIALI)

[CON  $\vec{x} = (x_1, x_2, \dots, x_m)$ ]

NELLE IPOTESI PRECEDENTI, LA FUNZIONE

$$g(\vec{x}) =_{\text{def}} \begin{cases} f_1(\vec{x}) & \text{SE } M_1(\vec{x}) \\ f_2(\vec{x}) & \text{SE } M_2(\vec{x}) \\ \vdots & \vdots \\ f_k(\vec{x}) & \text{SE } M_k(\vec{x}) \end{cases}$$

DEFINITA PER CASI E' CALCOLABILE

DIM. SIANO  $e_1, e_2, \dots, e_k$  TALI CHE

$$\begin{aligned} f_1 &= \phi_{e_1}^{(m)} \\ f_2 &= \phi_{e_2}^{(m)} \\ &\vdots \\ f_k &= \phi_{e_k}^{(m)} \end{aligned}$$

SUPPONIAMO CHE  $g(\vec{c}) \downarrow$ , CON  $\vec{c} = (c_1, c_2, \dots, c_m)$ .

ALLORA PER QUALCHE  $i$

- $M_i(\vec{c}) = \text{true}$  (E QUINDI  $M_j(\vec{c}) = \text{false}$ ,  $\forall j \neq i$ )
- $f_i(\vec{c}) \downarrow$  (E QUINDI  $(\exists y)(\exists t) S_m(e_i, \vec{c}, y, t)$ )
- $g(\vec{c}) = f_i(\vec{c})$

SI HA:  $(\exists y)(\exists t) S_m(e_i, \vec{c}, y, t)$

$$\leftrightarrow (\exists w) S_m(e_i, \vec{c}, (w)_1, (w)_2)$$

$$\leftrightarrow (\mu w) (S_m(e_i, \vec{c}, (w)_1, (w)_2)) \downarrow$$

POSTO  $\bar{w} = (\mu w)(S_m(l_i, \vec{c}, (w)_1, (w)_2))$ , SI HA

$$S_m(l_i, \vec{c}, (\bar{w})_1, (\bar{w})_2) = \underline{\text{true}}$$

DA CUI  $g(\vec{c}) = f_i(\vec{c}) = \phi_{l_i}^{(m)}(\vec{c}) = (\bar{w})_1$

MA POICHE' -  $M_i(\vec{c}) = \underline{\text{true}}$  ,  $\exists$

-  $M_j(\vec{c}) = \underline{\text{false}}$  ,  $\forall j \neq i$

SI HA, PER OGNI  $w \in N$ ,

$S_m(e_i, \vec{c}, (w)_1, (w)_2)$

$\Leftrightarrow (S_m(e_1, \vec{c}, (w)_1, (w)_2) \wedge M_1(\vec{c})) \vee \dots$

$\dots \vee (S_m(e_k, \vec{c}, (w)_1, (w)_2) \wedge M_k(\vec{c}))$

E QUINDI

$$g(\vec{c}) = (\bar{w})_1 = ((\mu w) (S_m(e_i, \vec{c}, (w)_1, (w)_2)))_1$$

$$= ((\mu w) ((S_m(e_1, \vec{c}, (w)_1, (w)_2) \wedge M_1(\vec{c})) \vee \dots$$

$$\dots \vee (S_m(e_k, \vec{c}, (w)_1, (w)_2) \wedge M_k(\vec{c}))))_1$$

D'ALTRA PARTE, SE  $g(\vec{c}) \uparrow$ , ALLORA PER QUALCHE  $i$

$$- M_i(\vec{c}) = \text{true} \quad (\text{E QUINDI } M_j(\vec{c}) = \text{false}, \forall j \neq i)$$

$$- f_i(\vec{c}) \uparrow \quad (\text{E QUINDI } (\exists y)(\exists t) S_m(e_i, \vec{c}, y, t) = \underline{\text{false}})$$

MA ALLORA

$$(\exists y)(\exists t) S_m(e_i, \vec{c}, y, t) = \underline{\text{false}}$$

$$\Leftrightarrow (\exists w) S_m(e_i, \vec{c}, (w)_1, (w)_2) = \underline{\text{false}}$$

$$\Leftrightarrow (\exists w) \left( (S_m(e_1, \vec{c}, (w)_1, (w)_2) \wedge M_1(\vec{c})) \vee \dots \right. \\ \left. \dots \vee (S_m(e_k, \vec{c}, (w)_1, (w)_2) \wedge M_k(\vec{c})) \right) = \underline{\text{false}}$$

$$\Leftrightarrow \left( (\forall w) \left( (S_m(e_1, \vec{c}, (w)_1, (w)_2) \wedge M_1(\vec{c})) \vee \dots \right. \right. \\ \left. \left. \dots \vee (S_m(e_k, \vec{c}, (w)_1, (w)_2) \wedge M_k(\vec{c})) \right) \right) \uparrow$$

PERTANTO SI HA, PER OGNI  $\vec{x}$ ,

$$g(\vec{x}) = \left( (\mu w) \left( \left( S_m(e_1, \vec{x}, (w)_1, (w)_2) \wedge M_1(\vec{x}) \right) \vee \dots \right. \right. \\ \left. \left. \dots \vee \left( S_m(e_k, \vec{x}, (w)_1, (w)_2) \wedge M_k(\vec{x}) \right) \right) \right)$$

DA CUI SEGUE LA CALCOLABILITA' DELLA

FUNZIONE  $g(\vec{x})$ . ■